

ABSTRACT

An optical pickup moves to the most inner circumference, then moves to outer circumference for a predetermined period and acquires address information there. Next, a difference XZ between the acquired address
5 information and predetermined reference address information is calculated, and then difference YZ between address information which is acquired by performing above mentioned process in standard acceleration/deceleration control algorithm setting stage and the predetermined reference address information is calculated. Feed control amount is multiplied by a ratio between difference XZ and
10 difference YZ.

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